Moho Interface Modeling Beneath the Himalayas, Tibet and Central Siberia
Using GOCO02S and DTM2006.0

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ABSTRACT

We apply a newly developed method to estimate the Moho depths and density contrast beneath the Himalayas, Tibet and Central Siberia. This method utilizes the combined least-squares approach based on solving the inverse problem of isostasy and using the constraining information from the seismic global crustal model (CRUST2.0). The gravimetric forward modeling is applied to compute the isostatic gravity anomalies using the global geopotential model (GOCO02S) and the global topo-bathymetric model (DTM2006.0). The estimated Moho depths vary between 60 - 70 km beneath most of the Himalayas and Tibet and reach the maxima of ~79 km. The Moho depth under Central Siberia is typically 50 - 60 km. The Moho density contrast computed relative to the CRUST2.0 lower crustal densities has the maxima of ~300 kg m⁻³ under Central Tibet. It substantially decreases to 150 - 250 kg m⁻³ under Himalayas and north Tibet. The estimated Moho density contrast under central Siberia is within 100 - 200 kg m⁻³.

Key words: Crust, Gravity, Himalaya, Isostasy, Moho interface, Tibet plateau


1. INTRODUCTION

Starting from the 1980s systematic studies of the lithospheric structure in the Himalayas and Tibet were carried out in the frame of the GGT, IRIS/1991-92PASSCAL and INDEPTH/GEODEPTH geophysical projects. Zhao et al. (1993) analyzed the seismic reflection data collected at the profile INDEPTH-I across the Himalayas. He estimated that the largest Moho depths reach ~75 km. This value is consistent with the values of 75 - 78 km along the INDEPTH-II seismic reflection profile obtained by Teng et al. (1983), Wu et al. (1995), and Gao et al. (2005). Zeng et al. (1994) reported the Moho depths to 80 - 84 km to the south of the Bangong-Nujiang suture. More recently, Schulte-Pelkum et al. (2005) reported the Moho depths to ~75 km beneath the Tethyan Himalayas. Kind et al. (2002) estimated based on processing the seismic data collected along the profile INDEPTH-III that the Tibetan crust varies in thickness from a maximum of about 78 ± 3 km to a minimum of about 65 ± 3 km; with the maximum thickness within the Lhasa terrane. Allègre et al. (1984), Wu et al. (1991), Nelson et al. (1996), and Kind et al. (1996) concluded that a typical crustal thickness under the Tibet plateau is 70 - 80 km with a probably partially molten crust beneath the depth of 20 - 30 km, characterized by high conductivity and a seismic low-velocity zone. Hirn et al. (1984) estimated that the average depth beneath the Lhasa terrane is ~55 km, while the average value of 70 km was suggested by Wu et al. (1995). Zhang et al. (2001) estimated the Moho depths in northern Tibet to be at least 80 km. Teleseismic receiver function analysis of seismograms recorded on a ~700 km long profile of 17 broadband seismographs traversing the north-west Himalayas conducted by Rai et al. (2006) revealed a progressive northward Moho deepening from ~40 km beneath Delhi south of the Himalayan fore deep to ~75 km beneath Taksha at the Karakoram fault. An earlier study by Wittlinger et al.
(2004) to the north of the Karakoram fault showed that the Moho continues to deepen to ~90 km beneath western Tibet before decreasing substantially to 50 - 60 km at the Altyn Tagh fault. Bagherbandi (2012) applied and compared three different isostatic methods (based on solving the Vening-Meinesz Moritz models and using Parker-Oldenburg’s algorithm) to estimate the Moho depths beneath Tibet and Himalayas. According to his results the maximum Moho depths reach 67 - 72 km depending on the method applied. The regional isostatic studies were conducted also by Lyon-Caen and Molnar (1983, 1984), Caporali (1995, 1998, 2000), Braitenberg et al. (2000a, b), Watts (2001), and others. The studies of the Siberian and Baikal crustal structures can be found, for instance, in Pavlenkova (1996), Zorin et al. (2002), and Pavlenkova and Pavlenkova (2006). In this study we apply a novel approach developed by Sjöberg (2009) and Sjöberg and Bagherbandi (2011) to estimate the Moho depths and density contrast. The numerical realization at the study area of the Himalayas, Tibet and Central Siberia is done using recently released global models of the Earth gravity, topography, bathymetry and crustal thickness. The gravimetric results are compared with the seismic model from the global crustal model CRUST2.0 as well as more detailed regional studies.

2. METHODOLOGY

Sjöberg and Bagherbandi (2011) developed and applied the least-squares method for a simultaneous estimation of the Moho depths and density contrast based on solving the inverse problem of isostasy and using the constraining information from seismic data. They formulated the linearized observation equations for the product of \( T\Delta \rho \) and \( \Delta \rho \) for as follows

\[
T(\Omega)\Delta \rho(\Omega) = \sum_{i=1}^{N_{\text{max}}} \sum_{m=0}^{n_{\text{max}}} \left[ \frac{2n+1}{4\pi G(n+1)} \Delta g_{m,n} \times \frac{n+2}{2} (\Delta \rho T^z)_{n,m} \right] \cdot Y_{m,n}(\Omega)
\]

(1)

and

\[
\Delta \rho(\Omega) = \frac{\Delta g'_{\rho}(r, \Omega)}{2\pi GT(\Omega)} \cdot \frac{1}{4\pi T(\Omega)} \left[ \sum_{n=0}^{n_{\text{max}}} \sum_{m=0}^{m_{\text{max}}} \left( \frac{1}{n+1} \cdot \frac{T_{0}/R}{2/(n+2) - T_{0}/R} \right) \Delta g_{m,n} \cdot Y_{m,n}(\Omega) \right]
\]

(2)

where \( T \) is the Moho depth; \( \Delta \rho \) is the Moho density contrast; \( G = 6.674 \times 10^{-11} \, \text{m}^3 \, \text{kg}^{-1} \, \text{s}^2 \) is the Newton gravitational constant; \( R = 6371 \times 10^3 \, \text{m} \) is the Earth mean radius; \( \Delta g' \) is the isostatic gravity anomaly; \( Y_{m,n} \) is the surface spherical harmonic function of degree \( n \) and order \( m \); and \( N_{\text{max}} \) is the upper summation index of spherical harmonics. The 3-D position is defined in the system of spherical coordinates \((r, \Omega)\); where \( r \) is the spherical radius and \( \Omega = (\phi, \lambda) \) denotes the spherical direction with the spherical latitude \( \phi \) and longitude \( \lambda \).

As seen from Eq. (2), if \( T \) is known, the crust-mantle density contrast \( \Delta \rho \) can be estimated from the spectrum of \( \Delta g' \). The isostatic gravity anomalies in Eqs. (1) and (2) are computed in the spectral domain using the following expression (Sjöberg 2009)

\[
\Delta g'_{m,n} = \frac{1}{4\pi} \left\{ \begin{array}{ll}
2\pi G \left( \rho^h \right)_{0,m} - \tilde{g}_0 & \text{if } n = 0 \\
2\pi G \left( \rho^h \right)_{n,m} - \Delta g_{m,n} & \text{otherwise}
\end{array} \right.
\]

(3)

where \( \Delta g_{m,n} \) and \( g'_{m,n} \) are the spherical harmonics of the gravity anomalies and isostatic gravity anomalies respectively; \( 2\pi G \left( \rho^h \right)_{n,m} \) is the spectral Bouguer gravity reduction term which is defined by means of the coefficients of global topographic/bathymetric (density) spherical functions \( \left( \rho^h \right)_{n,m} \). The density distribution function \( \rho^h \) equals \( \rho' \) on land, where \( \rho' \) is the reference crustal density. The ocean density contrast is defined as \( \rho = \rho' - \rho^- \); where \( \rho^- \) is the mean seawater density. The nominal compensation attraction (of zero-degree) \( \tilde{g}_0 \) stipulated at the sphere of radius \( R \) is computed as (cf. Sjöberg 2009)

\[
\tilde{g}_0 = g'_{0,0}(r, \Omega) \big|_{x=x} \approx -4\pi G \Delta \rho_o T_o
\]

(4)

where \( T_o \) and \( \Delta \rho_o \) are the adopted nominal mean values of the Moho depth and density contrast respectively.

The least-squares analysis combines the estimated product of \( T \) and \( \Delta \rho \) with the a priori values \( t \) and \( \kappa \) of these parameters in order to obtain the improved estimates of \( T \) and \( \Delta \rho \). The system of observation equations, formulated for both parameters, is written in the following vector-matrix form

\[
A \cdot x = l - e
\]

(5)

where \( e \) is the vector of residuals. The system matrix \( A \), the parameter vector \( x \) and the observation vector \( l \) are given by

\[
A = \begin{bmatrix} \kappa & t \\ 0 & 1 \end{bmatrix}, \quad x = \begin{bmatrix} d T \\ d \kappa \end{bmatrix}, \quad l = \begin{bmatrix} l_1 - t \kappa \\ l_2 - t \end{bmatrix}
\]

(6)

The elements \( l_1, l_2, \) and \( l_3 \), respectively, of the observation vector \( l \) are formed by the observables \( T \Delta \rho, \Delta \rho \) and \( T \). The parameter vector \( x \) consists of the unknown correcc-
tions $dT$ and $d\kappa$ to the a priori (initial) values of $T$ and $\Delta \rho$. The solution is found based on solving the system of normal equations $\mathbf{x} = \mathbf{N}^{-1}\mathbf{A}^T\mathbf{Q}^{-1}\mathbf{1}$, where $\mathbf{N} = \mathbf{A}^T\mathbf{Q}^{-1}\mathbf{A}$ is the normal matrix, and $\mathbf{Q}$ denotes the variance-covariance matrix.

3. ISOSTATIC GRAVITY ANOMALIES

The study area comprising the Himalayas, Tibet and Central Siberia is bounded by the parallels 20 and 60 arc-deg northern latitudes and the meridians 60 and 120 arc-deg eastern longitudes. The topography/bathymetry over the study area including a description of the major geological regions is shown in Fig. 1.

The global geopotential model (GOCO02S) and the global topographic/bathymetric model (DTM2006.0) were used to compute the isostatic gravity anomalies with a spectral resolution complete to degree 180 of the spherical harmonics. This computation was realized on a $1 \times 1$ arc-deg geographical grid of surface points. The coefficients of the combined GRACE and GOCE satellite global geopotential model GOCO02S (Goiginger et al. 2011) were used to generate the gravity anomalies. The normal gravity component was computed according to the GRS-80 parameters (Moritz 1980).

The recent studies based on a regional accuracy assessment of global geopotential models have shown that the combined satellite-only GRACE/GOCE solutions provide a substantial improvement of the Earth’s gravity field at a medium-wavelength part of gravity spectra (within the frequency band approximately between 100 and 250) when compared to satellite-only GRACE models (cf. e.g., Goiginger et al. 2011). A significant improvement of gravity spectra at medium wavelengths by GOCE data was also demonstrated based on comparison with the combined satellite-terrestrial gravitational model EGM08 (Pavlis et al. 2012). Test results (not shown herein) revealed that the differences between the GOCO02S and EGM08 gravity field reach as much as $\pm 60$ mGal within our study area.

The refined Bouguer gravity anomalies were obtained after applying the Bouguer gravity reduction to the GOCO02S gravity anomalies. The Bouguer gravity reduction was computed using the coefficients of the global topographic/bathymetric model DTM2006.0 (Pavlis et al. 2007). The average density of the upper continental crust 2670 kg m$^{-3}$ (cf. Hinze 2003) was adopted as the topographic and reference crustal density. For the adopted values of the reference crustal density 2670 kg m$^{-3}$ and the mean seawater density 1027 kg m$^{-3}$, the ocean density contrast equals 1643 kg m$^{-3}$.

The regional map of the GOCO02S gravity anomalies and the refined Bouguer gravity anomalies, both computed with a spectral resolution complete to degree 180 of the spherical harmonics, are shown in Figs. 2 and 3. The GOCO02S gravity anomalies are between -185 and 193 mGal. The refined Bouguer gravity anomalies vary from -569 to

Fig. 1. Topography/bathymetry of the study area.
233 mGal. The orogenic belt corresponding to the convergence between the Indian and Eurasian continental tectonic plates is the most pronounced in the gravity field (see Fig. 2). Here we observe large horizontal spatial gravity anomaly variations with positive values in the Himalayas and corresponding negative values along the Indus-Gangetic basin. The mostly positive gravity anomalies are seen also over Tibet. Further north, the Altyn Tagh fault and the Tarim and Qaidam basins are characterized mainly by the negative gravity anomalies. The gravity signal over Central Siberia is more likely associated with the rock structures of major geological provinces of shields, platforms and basins. Here the gravity anomalies have either small negative or positive values. Bouguer gravity reduction application substantially changed the gravity field over the mountains (see Fig. 3). The continental margins of the Indian plate are...
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4. MOHO PARAMETERS

The isostatic gravity anomalies were used to estimate the Moho parameters over the study area. The system of (linearized) observation equations was solved by applying the least-squares adjustment using the elements method. The initial values of the Moho depths were taken from CRUST2.0 (Bassin et al. 2000). The Moho density contrast was determined relative to the adopted reference crustal density of 2670 kg m\(^{-3}\). The observation vector \( l \) in Eq. (6) was composed of three observation types; namely \( l_t = T\Delta\rho \) [Eq. (1)], \( l_x = \Delta\rho \) [Eq. (2)], and \( l_s = T_s \) formed by the CRUST2.0 Moho depth values. The variance-covariance matrix \( Q \) in the least-squares estimation model reads (cf. Sjöberg and Bagherabndi 2011)

\[
Q = \begin{pmatrix}
\sigma_i^2 & \sigma_{i/t}^2 & 0 \\
\sigma_{i/t}^2 & \sigma_j^2 & 0 \\
0 & 0 & \sigma_l^2
\end{pmatrix}
\]

(7)

where \( \sigma_i \) and \( \sigma_j \) are the standard errors of the parameters \( T\Delta\rho \) and \( T \), respectively, and \( \sigma_{i/t} = \sigma_i^2 / t' + \sigma_j^2 (T\Delta\rho)^2 / t'' \). The standard error \( \sigma_1 \) of \( T\Delta\rho \) was computed using the following expression

\[
\sigma_1^2 = \sigma_{\text{iso},\rho}^2 \approx \left( \frac{\gamma_0}{4\pi G} \right) \sum_{\text{e.d.}} N_{\text{e.d.}}^2 \sigma_{\text{e.d.}}^2
\]

(8)

where \( \gamma_0 \) is the GRS-80 normal gravity, \( N_{\text{e.d.}} = (2n+1)(n-1)/(n+1) \), and \( \sigma_{\text{e.d.}} \) are the error degree potential coefficients. The CRUST2.0 Moho depths data are not provided with the standard error model. Hence, we assumed the representative uncertainties (i.e., standard error \( \sigma_1 \) in the matrix \( Q \)) of the Moho depth data of \(-20 \) km. This corresponds to relative Moho uncertainties of \(-30\% \) or more depending on the actual Moho depths. This value was chosen empirically based on a range of differences in the Moho depth estimated values under the Himalayas and Tibetan Plateau, as summarized in section 1. A realistic estimation of the Moho depth errors is obviously not simple. Čadek and Martinec (1991), for instance, estimated the uncertainties of the Moho depths in their global crust thickness model to be about \(-20\% \) (5 km) for the oceanic crust and \(-10\% \) (3 km) for the continental crust. The results of more recent seismic and gravity studies, however, revealed that these error estimates are too optimistic. Grad et al. (2009) demonstrated that the Moho uncertainties (estimated based on processing the seismic data) under Europe regionally exceed 10 km with the average error of more than 4 km. Much larger Moho uncertainties are to be expected over large parts of the world where seismic data are absent or insufficient (such as our study area).

The estimated Moho parameters on a 1 x 1 arc-deg grid within the study area are shown in Figs. 4 and 5. The Moho depths vary from 34 to 79 km. The Moho density contrast (determined relative to the adopted reference crustal density of 2670 kg m\(^{-3}\)) varies between 380 and 710 kg m\(^{-3}\).

5. DISCUSSION

The largest continental crustal thickness is confirmed under the Himalayas; the Moho depths there reach 79 km. The locations of large crustal thickness further extend under the Tibetan plateau with typical Moho depths of 70 - 75 km and the maxima found in northern Tibet. In Central Tibet, more shallow Moho depths of \(-65 \) km correspond with the Bangong-Nujiang suture. These results agree with the findings of Braitenberg et al. (2000b), Kind et al. (2002), and others (see section 1). There are several different theories explaining a large crustal thickness beneath the Tibetan plateau. The collision of the Indian and Eurasian plates, which began in Paleogene and continues today (at a rate to about 5 cm yr\(^{-1}\); cf. e.g., Bilham et al. 1997), have been forming the Himalayan and Tibetan orogenic belt. The geological structure of Tibet is characterized by several sub-plates that were successively accumulated into the Eurasian plate during Paleozoic and Mesozoic periods. The results of palaeomagnetic analysis acquired that these sub-plates were moved from the southern hemisphere during the Paleozoic period northward as the intervening ocean subducted and subsequently accreted to the Eurasian plate. The resulting sutures are marked by distinctive geological formations and fault zones. For more information describing the geological structures and tectonic configuration we refer readers to studies, for instance, by Allègre et al. (1984) and Molnar (1986). This collision resulted in the subduction of a large part of the oceanic crust underneath the Tibetan plateau. Zeng et al. (2002) observed multiple crustal subduction features under the Himalayas and southern Tibet. Tilman et al. (2003) reported that the front of the Indian lithospheric mantle was detached below the Qiantang block, where the asthenosphere ascended and was exchanged with the lithosphere. The geophysical evidences also indicate that the subducted crust of the Indian plate detached from its upper part while the Indian lithospheric mantle is assimilating into the upper mantle (cf. Wu et al. 2004). Xu et al. (2004) reported that the Indian lithospheric slab is being subducted underneath the Tanggula Mountains. A large high-velocity anomalous zone was split into separate high-velocity anomalous bodies, which may be considered geophysical evidence for the abruption caused by the subduction of the Indian lithospheric mantle. The studies by Wittlinger et al. (2004) and Rai et al. (2006) suggest that the Indian plate may penetrate as far...
as the Bangong suture, and possibly as far north as the Altyn Tagh. Alternative theories facilitate the hypothesis of crustal shortening and consequent crust thickening attributed to the extrusion or escape tectonics mechanism (Molnar and Tapponnier 1975). According to these theories the motion of the Indian plate pressed the Indochina block, and a proposed mechanism is that a large part of the crustal shortening was accommodated by thrusting and folding of the sediments of the passive Indian margin together with the deformation of the Tibet crust (Dewey et al. 1989).

Large crustal thickness of 60 - 65 km was confirmed also beneath the Altay and Hindu Kush. These features are in the contrast to large basins to the south and southwest of the Himalayas as well as to the north of Tibet with a much thinner continental crust. The Moho depths beneath the Tarim and Qaidam basins were found to be below ~60 km. The
similar Moho depths estimates under the Tarim basin were
given, for instance, by Wittlinger et al. (2004). The Indo-
Gangetic basin has a crustal thickness of 45 - 55 km. Ac-
cording to our estimates the crustal thickness beneath Central
Siberia is typically 50 - 60 km with some more detailed
structures of deeper crustal roots. The crustal structure of
Central Siberia consists of two distinctive tectonic regions,
the Paleozoic west Siberian basin and the Precambrian Si-
berian Craton (which extends from the Ural orogen to the
Lena river basin). Tectonic configuration indicates that
the crustal evolution of these regions began approximately
4 Ga ago. The Moho depths beneath Archean terranes were
estimated to be 60 - 65 km. The crustal thickness slightly
decreases under Paleo-Mesoproterozoic terranes and Me-
sozoic and Cenozoic regions, where the Moho depths are
typically less than 60 km. The largest Moho depths of 61 -
64 km were found at the southern part of the Siberian Craton.
The Moho depths beneath the Paleozoic west Siberian basin
are according to our estimates ~53 km. Some more detailed
structures of the crustal thickness can be recognized along
the Baikal rift zone which is a boundary between the Amur
sub-plate and the Eurasian plate (Wei and Seno 1998). Here
the Moho locally deepens to ~62 km.

We further compared our estimates (re-sampled to 2 ×
2 arc-deg grid) with the CRUST2.0 Moho depths. The dif-
ifferences between our and CRUST2.0 Moho depths are
shown in Fig. 6. These differences within the study area
vary between -9.0 and 18.3 km with the mean of -3.4 km
and the RMS of differences is 5.7 km. As seen from this
comparison, the largest absolute differences are found in
Himalayas (differences are mostly > 10 km). Our results
more closely correspond with the CRUST2.0 Moho depths
under Siberia (differences are mainly within ±5 km). The
CRUST2.0 and our estimates of the crustal thickness be-
neath Central Siberia are, however, substantially larger than
the Moho depths derived from seismic data, for instance, by
Pavlenkova (1996), Zorin et al. (2002) and Pavlenkova and
Pavlenkova (2006). They reported a typical thickness of the
Siberian crust of 35 - 45 km.

The largest values of the Moho density contrast (de-
finite relative to the reference crustal density of 2670 kg m⁻³)
are under the Himalayan and Tibetan orogens. Here the
maxima exceed 550 kg m⁻³ and locally reach as much as
~700 kg m⁻³. Since the Moho density contrast was deter-
mined with respect to the reference crustal density (of
2670 kg m⁻³), the density of the upper mantle underlying
the crust can be calculated from these values. The estimated
upper mantle density under Himalayas and Tibet is typically
3200 - 3400 kg m⁻³. The continental upper mantle density
increases with depth. The largest values are thus under sig-
nificant orogens with the largest crustal thickness. We fur-
ther used these upper mantle density values to determine the
Moho density contrast with respect to the CRUST2.0 lower
crustal densities. These values should optimally represent
the real Moho density contrast. The Moho density contrast
under the continental crust in this case generally does not
increase everywhere with depths. Its maxima are found be-
neath central Tibet; here the density contrast is ~300 kg m⁻³.
The Moho density contrast, however, substantially decreases
to 150 - 250 kg m⁻³ under the deepest mountain roots of
Himalayas and north Tibet. The Moho density contrast in
Central Siberia is typically within 100 - 200 kg m⁻³.

Fig. 6. Moho depth differences obtained from the combined approach and CRUST2.0. The units are in km.
6. CONCLUSIONS

The convergent tectonic plate boundaries marked distinctively by the positive gravity anomalies along the orogens are coupled with the negative gravity anomalies along the sides of subducted crust. In the gravity map these features are seen along the continent-to-continent collision zone of the Indian and Eurasian tectonic plates (Himalayan orogen and the Indo-Gangetic basin). The large positive gravity anomalies over the Tibetan, Altay and Hindu Kush orogens are coupled by the negative gravity disturbances over the Tarim and Qaidam basins.

Bouguer gravity reduction application substantially changed the gravity signal over Himalayas and Tibet with the gravity anomaly minima below -500 mGal. The resulting refined Bouguer gravity anomalies are significantly correlated with the Moho geometry. The largest crustal thickness was confirmed under the Himalayan and Tibetan orogens with the Moho depths exceeding 65 km and reaching the maxima of ~70 km. This maximum Moho depth differs ~10% from the corresponding maximum of 72 km estimated based on using EGM08 and DTM2006.0 by Bagherbandi (2012). The contrast between the crustal thickness beneath orogens and basins is clearly distinguished by more shallow Moho depths (< 60 km) under Indo-Gangetic, Tarim and Qaidam basins. Our estimates of the Siberian crustal thickness are similar to CRUST2.0 Moho depths, but both are significantly larger than that obtained from regional seismic studies. This misfit between the regional and global seismic models might be explained by a low quality of CRUST2.0 in this part of the world. Consequently, our gravimetric solution, complied using the CRUST2.0 Moho depths in forming the observation equations, agree better with CRUST2.0 than with regional seismic results.

The Moho density contrast typically increases with depth. However, this trend is not representative everywhere under the continental crust. Our results revealed that the density contrast of the deepest crustal structures is often much less pronounced compared to the upper mantle. When taking into consideration the Moho density contrast computed with respect to the CRUST2.0 lower crustal densities the maxima of ~300 kg m$^{-3}$ are found under Central Tibet. On the other hand, the Moho density contrast under the deepest crustal structures of the Himalayas and northern Tibet is only 150 - 250 kg m$^{-3}$. The Moho density contrast of 100 - 200 kg m$^{-3}$ was estimated over most of Central Siberia.

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